



COMENIUS UNIVERSITY IN BRATISLAVA
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EQUILOADED AUTOMATA

Master's Thesis

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Bratislava, 2010

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Bc. Ivan Kováč

I hereby declare that I wrote this thesis by myself, only with the help of the referenced literature, under the careful supervision of my thesis advisor.

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Abstract

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In this thesis we initiate the study of a balanced use of resources in computations. We consider a particular model of computation — deterministic finite automata — and take states as the resource to be used in a balanced way. In this setting we develop notions and prove results which can serve as an example for similar studies in other settings. Three possible approaches to define a balanced use of states by deterministic finite automaton are investigated: *a strict equiloadedness*, *an equiloadedness*, and *an equiloadedness on sequences of words*. We analyze properties of families of automata and languages with respect to different definitions of balanced use of states.

We show a characterization of the family of languages for which there exists a strictly equiloaded automaton. We exhibit the closure properties of this family based on this characterization.

The family of languages for which there exists an equiloaded automaton is analyzed by proving closure properties, by providing a necessary condition for a language to be in this family, and by defining a set of transformations that preserve the equiloadedness of an automaton.

Considering equiloadedness on sequences of words, we analyze the influence of different orderings of words on the equiloadedness tolerance. We investigate the equiloadedness on sequences for various bounds on the equiloadedness tolerance function.

KEYWORDS: equiloaded automata, balanced use of resources, deterministic finite automata

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Chapter 1

Introduction

Our research is motivated by balancing resources in computations. A balanced use of resources can be important in many real-world problems. For example, it is desirable that all parts of a system (e.g., processor chip) are used so that none of the parts wears out substantially faster (or heats up more) than other parts.

Since this topic has not been investigated yet, it is necessary to develop the basic notions for this type of study. We have chosen a simple model of computation, deterministic finite automaton, and its natural resource, the state.

Deterministic finite-state automaton is a well known computation model. It has good properties for our research, for example on a word w , there are always $|w| + 1$ usages of states. Many problems in automata theory are at first studied on this simple model and then extended to more complex models such as pushdown automata, linear-bounded automata or even Turing machines.

We define a new property of finite automata, *equiloaderiness*: the balanced use of each state of an automaton. We shall explore three ways of defining this notion.

The Structure of Thesis

In Chapter 2 we define a deterministic finite automaton and related concepts, which is a computational model used throughout the thesis.

In Chapter 3 we start with a basic definition by which an automaton is strictly equiloader if it uses every state equally often (except for a constant difference) on every word from the language accepted. We are able to characterize all strictly equiloader automata, see Section 3.3.

In Chapter 4 we introduce a different definition of an equiloader automaton — an automaton is equiloader if, for each given length n , it uses its states equally often during computations in total over words of length n from the language accepted. We describe a set of automata transformations, which do not change the equiloaderiness property. We provide a necessary condition for a language to be in the family of languages accepted by equiloader automata. We prove closure properties of this family. Finally, we conjecture a sufficient condition for an automaton to be equiloader. If it holds, this

conjecture would lead to infinite number of non-trivial equiloaded automata.

In Chapter 5 we analyze equiloadedness on sequences of words. This setting is motivated by a batch processing of an input. We do not require that an automaton uses its states equally often on all words. We rather determine some checkpoints where the states must be used equally often, up to the equiloadedness tolerance. In this chapter we answer questions about the impact of different orderings of words on equiloadedness on sequences of words.

We conclude by stating several open problems about equiloadedness and indicate several possibilities for continuing this research.

Chapter 2

Preliminaries

In this chapter, we present the definition of deterministic finite automaton (DFA) used in this thesis. We use the definition of DFA such that an automaton can halt without reading an input word to the end.

We use the halting DFA because we are only interested in the load of states while processing words from the accepted language. Words not from the accepted language, and thus rejected by the DFA, are not relevant to our analysis. The “dead state” used to finish reading input words will thus not distort the balanced use of other states. It is possible to study the balanced use of resources on non-halting DFA, but we find this setting more interesting.*

Throughout the thesis, we assume that the set of natural numbers \mathbb{N} contains 0.

Definition 2.1. A *deterministic finite automaton* A is a 5-tuple $A = (Q, \Sigma, \delta, q_0, F)$ consisting of a finite set of states Q with an initial state $q_0 \in Q$, a finite alphabet Σ , a transition function $\delta : Q \times \Sigma \rightarrow Q$, and a set of accepting states $F \subseteq Q$.

Remark. In our version of DFA (halting DFA), we shall consider the transition function to be a partial function.

Definition 2.2. A *configuration* of the DFA A is a pair $(q, w) \in Q \times \Sigma^*$, where q is a state of the automaton and w is the remaining part of the input.

Definition 2.3. A *computation step* of the DFA A is a relation \vdash_A on configurations defined by

$$(q, av) \vdash_A (p, v) \stackrel{\text{def}}{\iff} p = \delta(q, a).$$

Remark. If it is clear from the context which automaton we mean, we shall use \vdash instead of \vdash_A . We shall denote the reflexive and transitive closure of \vdash_A by \vdash_A^* .

Definition 2.4. A *language* accepted by the deterministic finite automaton A is the set of words $L(A) = \{w \in \Sigma^* \mid (q_0, w) \vdash_A^* (q, \varepsilon), q \in F\}$.

*For strict equiloading used in Chapter 3 it is not hard to see that languages for which there is a strict equiloading automata form “trivial” family of languages – all over one letter alphabet and of very specific form.

Some of our results are based on a graphical representation of a DFA. For the sake of completeness we shall define the term graphical representation.

Definition 2.5. Let $A = (Q, \Sigma, \delta, q_0, F)$ be a DFA. A *graphical representation* of the DFA A is the directed labelled graph $G(V, E)$, $V = Q$, with a marked set of vertices F and an *initial* vertex q_0 , where a set of arcs is defined as follows:

- There is an arc $(p, q) \in E$ labeled by x if and only if $\delta(p, x) = q$ for some $x \in \Sigma$. Moreover, the number of arcs from p to q is equal to the number of different $x \in \Sigma$ such that $\delta(p, x) = q$.

Remark. We shall draw the non-accepting states in the graphical representation of A as circles and accepting states as double circles. The initial vertex q_0 shall be marked with one additional input arc. The reader can see a graphical representation of a DFA at Figure 3.2 in the next chapter.

We shall use the term minimal-state automaton in respect to Myhill-Nerode Theorem. [Nerode, 1958]

Theorem 2.1 (Myhill-Nerode). Let $L \subseteq \Sigma^*$ be a language. The following statements are equivalent.

1. L is a regular language.
2. There is a right-invariant equivalence relation \sim of finite index such that L is a union of some of the equivalence classes of \sim .
3. A relation \sim_L defined by $u \sim_L v \iff (\forall x \quad ux \in L \iff vx \in L)$ is of finite index.

Definition 2.6. Let L be a regular language. An automaton $A = (Q, \Sigma_L, \delta, q_0, F)$ is said to be *the minimal-state automaton* for the language L , if it is defined as follows. The states of A are the equivalence classes of \sim_L with $\varepsilon \in q_0$. The set of accepting states consists of equivalence classes such that $L = \bigcup_{q \in F} q$. The transition function δ is defined by

$$\delta(p, x) = q \stackrel{\text{def}}{\iff} \forall w \in p \quad wx \in q.$$

Chapter 3

Strictly Equiloaded Automata

In this chapter, we shall analyze properties of strictly equiloaded automata as defined in [Kováč, 2008]. We define the concept of strictly equiloaded automata. We show two results from [Kováč, 2008], relationship with minimal-state automaton and strict equiloadedness of finite languages. Finally, we characterize the family of languages for which there exists a strictly equiloaded automaton. Using this characterization we prove closure properties of the family of languages accepted by equiloaded automata.

3.1 Definition and Equivalent Form

A very strict view of a balanced use of states is that on every word in the accepted language all states are used equally many times. We shall relax this condition by an equiloadedness tolerance or equiloadedness constant* in such a way, that difference between load of any two states is less than the equiloadedness tolerance.

Notation. Let A be a DFA and w be a word from $L(A)$. We denote by $\#_A[q, w]$ (or simply by $\#[q, w]$) the number of times the automaton A uses the state q when processing the input w .

Definition 3.1 (Strict equiloadedness). Let $A = (Q, \Sigma, \delta, q_0, F)$ be a deterministic finite automaton. The automaton A is *strictly equiloaded* at words from $L = L(A)$ if there exists $k \in \mathbb{R}^+$ such that

$$\forall w \in L, \forall p, q \in Q \quad |\#[p, w] - \#[q, w]| \leq k.$$

The smallest k for which this inequality holds will be called an *equiloadedness constant*.

Remark. Instead of writing “ A is strictly equiloaded at words from $L(A)$ ” we shall simply write “ A is strictly equiloaded”.

Notation. The family of languages for which there is some strictly equiloaded automaton is denoted by $\mathcal{L}_{\text{SEQA}}$.

*In Chapter 5 we shall use the term equiloadedness tolerance for a function, thus for the sake of clarity we shall now use the term equiloadedness constant

Example 3.1. The language $L = \{a^{3i+2} \mid i \in \mathbb{N}\}$ belongs to the family $\mathcal{L}_{\text{SEQA}}$. In Figure 3.1(a) we can see the minimal-state automaton A for the language L . Because all computations on words from $L(A)$ end in the state q_2 , every state is equally loaded on any $w \in L(A)$. Hence, the equiloading constant for A is $k_A = 0$.

On the other hand, there is no strictly equiloading automaton for the language $L' = \{wabav \mid w, v \in \Sigma^*\}$. In Figure 3.1(b) is the minimal-state automaton B that accepts this language. It is easy to prove non-equiloadingness of the automaton B — on words $abav \in L'$ is the accepting state q_3 used $|v|$ times and the state q_0 only once, thus there is no constant k such that, for any length $n = |v| + 3$, it holds $||v| - 1| \leq k$. It can be proved from Theorem 3.1 that no strictly equiloading minimal-state automaton implies non-existence of strictly equiloading automaton.

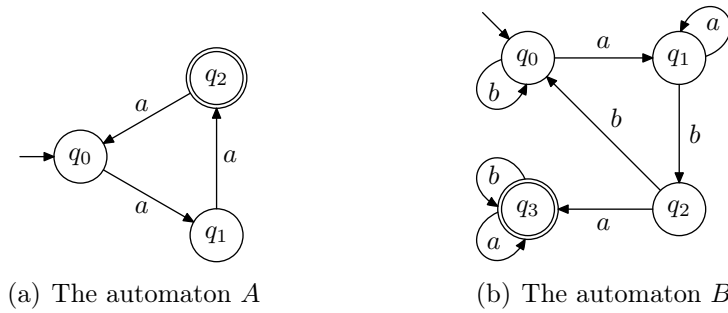


Figure 3.1: An example of (a) a strictly equiloading and (b) a non-strictly equiloading automaton

Now, we shall provide an equivalent form of the condition of strict equiloadingness from the above definition.

Lemma 3.1. A DFA $A = (Q, \Sigma, \delta, q_0, F)$ is strictly equiloading at words from $L = L(A)$ if and only if there exists $k_1 \in \mathbb{R}^+$ such that

$$\forall w \in L \quad \left| \max_{q \in Q} (\# [q, w]) - \frac{|w| + 1}{|Q|} \right| \leq k_1. \quad (3.1)$$

Remark. The fraction $(|w| + 1)/|Q|$ expresses the average load of states on the word w , since there are $|w| + 1$ states used and $|Q|$ is the number of states. Hence, when deciding whether an automaton A is equiloading, it suffices to compute the average load and compare it with the load of the most used state.

Proof. If A is strictly equiloading, for all $w \in L(A)$ it holds $|\# [p, w] - \# [q, w]| \leq k$. Hence, if we choose p to be the most used state and q to be the least used state, it holds that

$$\forall w \in L(A) \quad \left| \max_{q \in Q} (\# [q, w]) - \frac{|w| + 1}{|Q|} \right| \leq \left| \max_{q \in Q} (\# [q, w]) - \min_{q \in Q} (\# [q, w]) \right| \leq k$$

Conversely, if (3.1) holds, then the load of the most used state q_{\max} is bounded from above by $(|w| + 1)/|Q| + k_1$ and the load of the least used state q_{\min} is bounded from

below by $(|w| + 1)/|Q| - k_1 \cdot (|Q| - 1)$. Thus, for a difference between the load of any two states it holds that $|\#[p, w] - \#[q, w]| \leq |\#[q_{max}, w] - \#[q_{min}, w]| \leq k_1|Q| = k$. \square

3.2 Elementary Results

For the sake of completeness we shall present two theorems from [Kováč, 2008]. The first theorem provides a strong principle for proving the strict equiloadingness of an automaton.

Theorem 3.1. A regular language L is in $\mathcal{L}_{\text{SEQA}}$ if and only if the minimal-state automaton for L is strictly equiloading.

Proof. A proof can be found in [Kováč, 2008]. \square

Theorem 3.2. Every finite language L is in the family $\mathcal{L}_{\text{SEQA}}$.

Proof. Consider the minimal-state automaton A for the language L . The automaton A has no cycles, hence on every word is each state used once or not at all. Thus $|\#[p, w] - \#[q, w]| \leq 1$. \square

3.3 Characterization

Theorem 3.3 (Characterization of $\mathcal{L}_{\text{SEQA}}$). Every language $L \in \mathcal{L}_{\text{SEQA}}$ is either finite or a graphical representation of any equiloading automaton that accepts L is an oriented multicycle through all states.

Remark. By an oriented multicycle through all states we mean an automaton with transition function defined by $\delta(q_i, x) = q_{(i+1) \bmod k}$, where $x \in \Sigma$. For the state q_i , it is possible that there exists more than one symbol from Σ for which transition function is defined. See example 3.2.

Proof. Suppose that L is an infinite language accepted by an equiloading automaton $A = (Q, \Sigma, \delta, q_0, F)$. We will show that A must contain a multicycle through all states. If it does not contain one, we know that A is either acyclic (thus, $L(A)$ is a finite language) or there is a cycle C which does not contain all states. Let u be a substring such that, when A processes u , A changes its state from q_0 to q_c , where q_c lies in the cycle C . Let v be a substring such that A (when it processes v) starts at the state q_c , visits all states from the cycle, and returns to the state q_c . Let w be a substring such that A changes its state from f_c to an accepting state. If such a substring does not exist, then the load of q_c on every word is equal to zero. Therefore A is not strictly equiloading.

If w exists, then at word uv^kw the DFA A will not be strictly equiloading. This implies that in A must exist a multicycle through all states.

Now suppose that there exists a transition at symbol x , such that A will change its state from (current) q_i to q_j , where $j \neq i + 1$. It means that there is another cycle in A , but not through all of its states. So we can use the same principle of constructing input for A as above. It can be shown that A is not a strictly equiloading automaton, a contradiction. Therefore, a graphical representation of A is a multicycle through all states. \square

Example 3.2. The automaton $A = (\{q_0, q_1, q_2, q_3\}, \{a, b, c\}, \delta, q_0, \{q_2\})$ shown in Figure 3.2, where δ is defined by

$$\begin{aligned} \delta(q_0, a) &= q_1, & \delta(q_1, a) &= \delta(q_1, c) = q_2, \\ \delta(q_2, b) &= q_3, & \delta(q_3, a) &= q_0, \end{aligned}$$

is a multicycle. Thus, the language $L = \{aaba, acba\}^* \cdot \{ac, aa\}$ is strictly equiloading.

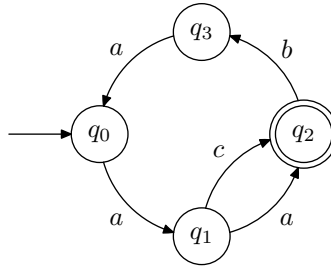


Figure 3.2: The automaton A for $L = \{aaba, acba\}^* \cdot \{ac, aa\}$

Example 3.3. Based on our characterization of the family $\mathcal{L}_{\text{SEQA}}$ it is easy to see that there are many regular languages not in this family. For example, any language of words that contain some substring, e.g., $L = \{wabbav \mid w, v \in \Sigma^*\}$. It is unfortunate, but we can not expect that all regular language will be (strictly) equiloading.

3.4 Closure Properties

As we shown in [Kováč, 2008], languages accepted by strictly equiloading automata are not closed under inverse homomorphism, union, Kleene star, Kleene plus, concatenation and complement. Now we shall examine three additional closure properties. In particular, we show that $\mathcal{L}_{\text{SEQA}}$ is not closed under homomorphism and reversal, and it is closed under intersection. Two of this results follows directly from the characterization of languages accepted by strictly equiloading automata provided by Theorem 3.3.

Theorem 3.4. The family $\mathcal{L}_{\text{SEQA}}$ is not closed under homomorphism.

Proof. Let $A = (\{q_0\}, \{a, b\}, \delta, q_0, \{q_0\})$ be a DFA, where $\delta(q_0, a) = \delta(q_0, b) = q_0$. The language accepted by the automaton A is $L = L(A) = \{a, b\}^*$. Consider a homomorphism h defined by $h(a) = aab$ and $h(b) = aa$. We would show that the language

$h(L(A)) = \{aax \mid x \in \{\varepsilon, b\}\}^*$ is not equiloading. The minimal-state automaton for this language is $B = (\{q_0, q_1, q_2\}, \{a, b\}, \delta_B, q_0, \{q_2\})$, where the transition function is defined by $\delta_B(q_0, a) = q_1$, $\delta_B(q_2, a) = q_1$, $\delta_B(q_1, a) = q_2$, and $\delta_B(q_2, b) = q_0$. The automaton B is not equiloading. (For example, at the word $h(b^k) = a^{2k}$.) \square

Theorem 3.5. The family $\mathcal{L}_{\text{SEQA}}$ is not closed under reversal.

Proof. Consider the language $L = \{(abb)^i x \mid x \in \{a, \varepsilon\}, i \in \mathbb{N}\}$. The graphical representation of the minimal-state automaton $A_1 = (\{q_0, q_1, q_2\}, \Sigma, \delta_1, q_0, \{q_0, q_1\})$ for L is an oriented multicycle, hence $L \in \mathcal{L}_{\text{SEQA}}$. (The transition function δ_1 is defined as follows. $\delta_1(q_0, a) = q_1$, $\delta_1(q_1, b) = q_2$ and $\delta_1(q_2, b) = q_0$.) Yet, the minimal-state automaton $A_2 = (Q, \Sigma, \delta_2, q_0, \{q_0, q_1\})$ for L^R is not strictly equiloading. The automaton A_2 has four states, and the transition function δ_2 is defined by

$$\begin{aligned} \delta_2(q_0, a) &= q_1, & \delta_2(q_0, b) &= q_2, & \delta_2(q_1, b) &= q_2, \\ \delta_2(q_2, b) &= q_3, & \delta_2(q_3, a) &= q_1. \end{aligned}$$

Therefore, the graphical representation of A_2 is not an oriented multicycle and A_2 is not strictly equiloading. \square

Theorem 3.6. The family $\mathcal{L}_{\text{SEQA}}$ is closed under intersection.

Proof. If at least one of $L_1, L_2 \in \mathcal{L}_{\text{SEQA}}$ is finite, the intersection $L_1 \cap L_2$ is finite and thus is in $\mathcal{L}_{\text{SEQA}}$. Let A, B be automata accepting L_1 and L_2 respectively. If we use the standard construction[†] of an automaton from the intersection of two languages, then the result (call it C) will be either a multicycle (suppose we remove states that C never visits) or $L(C)$ will be finite. If $L(C)$ is finite, then $L(C)$ is also strictly equiloading. Suppose that $L(C)$ is infinite. If there is a state (p, q) such that there exist states (p_1, q_1) and (p_2, q_2) such that

$$\delta_C((p, q), x) = (p_1, q_1), \quad \delta_C((p, q), y) = (p_2, q_2).$$

Thus $p_1 = p_2$ and $q_1 = q_2$ (both A and B are multicycles). Similarly, if there is a state (p, q) such that there exist states (p_1, q_1) and (p_2, q_2) such that

$$\delta_C((p_1, q_1), x) = (p, q), \quad \delta_C((p_2, q_2), y) = (p, q),$$

then $p_1 = p_2$ and $q_1 = q_2$. Thus, C is a multicycle and equiloading. \square

By above theorems and results in [Kováč, 2008], we can summarize the closure properties of $\mathcal{L}_{\text{SEQA}}$. The family $\mathcal{L}_{\text{SEQA}}$ is closed under intersection and it is not closed under homomorphism, inverse homomorphism, union, concatenation, Kleene star, Kleene plus, reversal and complement. The overview of closure properties of families \mathcal{R} , $\mathcal{L}_{\text{SEQA}}$ and $\mathcal{L}_{\text{EQA}}^\ddagger$ is shown in Table 4.1.

[†]States of the new automaton are pairs of states from A and B respectively. There is a transition from (p, q) to (p', q') on a symbol x if and only if $\delta_A(p, x) = p'$ and $\delta_B(q, x) = q'$.

[‡]Defined in the next chapter.

Chapter 4

Equiloaded Automata

In this chapter, we shall discuss a relaxation of the strict definition of an automaton which uses its states in a balanced way in total over all words of each given length n . The relaxation of the property of strict equiloadedness gives us new non-trivial automata which are equiloaded. We shall define some transformations of automata which preserve the equiloadedness property and analyze properties of equiloaded automata and the family of languages accepted by equiloaded automata.

4.1 Definition and Equivalent Form

Notation. Let A be a DFA and L' be a language, $L' \subseteq L(A)$. We denote by $\#_A[q, L']$ (or simply by $\#[q, L']$, if it is clear from the context which automaton we mean) the number of times the automaton A uses the state q when processing the inputs from L' . It holds that

$$\#_A[q, L'] = \sum_{w \in L'} \#_A[q, w].$$

Definition 4.1 (Equiloadedness). Let $A = (Q, \Sigma, \delta, q_0, F)$ be a deterministic finite automaton. The automaton A is *equiloaded* at words from $L = L(A)$ if there exists $k \in \mathbb{R}^+$ such that

$$\forall n \in \mathbb{N}, \forall p, q \in Q \quad |\#[p, L \cap \Sigma^n] - \#[q, L \cap \Sigma^n]| \leq k|L \cap \Sigma^n|.$$

The smallest k for which this inequality holds will be called the *equiloadedness constant*.

Remark. The factor $|L \cap \Sigma^n|$ on the right side of the inequality expresses the possibility of one state to be used constantly more than other on every word. Without this factor, there will be a strictly equiloaded automaton which is not equiloaded.

Notation. The family of languages L for which there is an equiloaded automaton will be denoted by \mathcal{L}_{EQA} .

Example 4.1. Consider the language $L = \{a^i b^j \mid i, j \in \mathbb{N}\}$. The minimal-state automaton A for this language shown in Figure 4.1(a). This automaton is equiloading, as is shown in the proof of Theorem 4.1. Intuitively, for each word $a^i b^j$ there is a word $a^j b^i$ of the same length and automaton A uses each state approximately $i + j$ times.

In Figure 4.1(b) there is a non-equiloading automaton B . It can be shown that the load of the state q_0 on words of a given length $n = 3\ell$ is $(\ell + 1)|L \cap \Sigma^n|$. The average load of states on words of the length 3ℓ is $(3\ell + 1)|L \cap \Sigma^n|/5$. From Lemma 4.1 and from above we can prove that B is not equiloading, because for any constant k there is ℓ such that $(\ell + 1) - (3\ell + 1)/5 > k$. However, this does not mean that the language $L(B) = \{aaa, bbb\}^*$ is not equiloading.

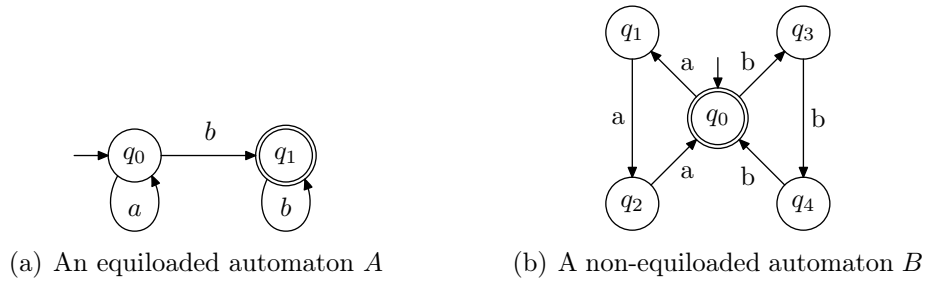


Figure 4.1: Example of (a) an equiloading and (b) a non-equiloading automaton

Similarly to the strict equiloading case, we provide an equivalent form of our definition. This form is mostly used in proofs of equiloading of an automaton because it is easier to consider the most used state rather than compare all possible pairs of states.

Lemma 4.1. A DFA $A = (Q, \Sigma, \delta, q_0, F)$ is equiloading at words from $L = L(A)$ if and only if there exists $k_1 \in \mathbb{R}^+$ such that

$$\forall n \in \mathbb{N} \quad \left| \max_{q \in Q} (\#[q, L \cap \Sigma^n]) - \frac{(n+1) \cdot |L \cap \Sigma^n|}{|Q|} \right| \leq k_1 |L \cap \Sigma^n|. \quad (4.1)$$

Remark. The left side of the inequality (4.1) can be read as a difference between the load of the most used state and the average load of states at all words from L of a given length n . For all n where $L \cap \Sigma^n \neq \emptyset$, the inequality (4.1) can be written as

$$\frac{\max_{q \in Q} (\#[q, L \cap \Sigma^n])}{|L \cap \Sigma^n|} - \frac{n+1}{|Q|} \leq k_1.$$

Seeing that in the case where $L \cap \Sigma^n \neq \emptyset$, the inequality holds, we shall use the above forms of the equiloading condition as needed.

Proof. If A is equiloading, it holds that

$$\forall n \in \mathbb{N} \quad \left| \max_{q \in Q} (\#[q, L \cap \Sigma^n]) - \min_{q \in Q} (\#[q, L \cap \Sigma^n]) \right| \leq k |L \cap \Sigma^n|.$$

Since the least used state is used at most as many times as the average load of states, the inequality (4.1) is valid.

Conversely, suppose that the inequality (4.1) holds. For a given n , let q_{max} be the most used state. A load of each state at words from $L \cap \Sigma^n$ is bounded from above by $\# [q_{max}, L \cap \Sigma^n]$ and therefore by

$$\frac{(n+1)|L \cap \Sigma^n|}{|Q|} + k_1|L \cap \Sigma^n|.$$

On the other hand, the load of every state is bounded from below by

$$\frac{(n+1)|L \cap \Sigma^n|}{|Q|} - k_1|L \cap \Sigma^n|(|Q| - 1).$$

If we use these bounds in $|\#[p, L \cap \Sigma^n] - \#[q, L \cap \Sigma^n]|$, we obtain

$$|\#[p, L \cap \Sigma^n] - \#[q, L \cap \Sigma^n]| \leq k_1|L \cap \Sigma^n| + k_1|L \cap \Sigma^n|(|Q| - 1) \leq k_1|Q| \cdot |L \cap \Sigma^n|.$$

Since $k = k_1|Q|$ is a constant, A is equiloading. \square

4.2 Elementary Results

Theorem 4.1. $\mathcal{L}_{\text{SEQA}} \subsetneq \mathcal{L}_{\text{EQA}} \subsetneq \mathcal{R}$.

Proof. Consider $L \in \mathcal{L}_{\text{SEQA}}$. There exists a strictly equiloading automaton A such that $L = L(A)$. Since $|\#[p, w] - \#[q, w]| \leq k$ for all $p, q \in Q$, for all n it holds that

$$\begin{aligned} |\#[p, L \cap \Sigma^n] - \#[q, L \cap \Sigma^n]| &= \left| \sum_{w \in L \cap \Sigma^n} (\#[p, w] - \#[q, w]) \right| \\ &\leq \sum_{w \in L \cap \Sigma^n} |\#[p, w] - \#[q, w]| \leq k|L \cap \Sigma^n|. \end{aligned}$$

We showed that $\mathcal{L}_{\text{SEQA}} \subseteq \mathcal{L}_{\text{EQA}}$. To show that $\mathcal{L}_{\text{SEQA}} \neq \mathcal{L}_{\text{EQA}}$ it suffices to show that a language $L = \{a^i b^j \mid i, j \in \mathbb{N}\}$ is in \mathcal{L}_{EQA} . Let $A = (\{q_0, q_1\}, \{a, b\}, \delta, q_0, \{q_0, q_1\})$ be the minimal-state automaton for the language L . It is easy to see that the minimal-state automaton A for L is not strictly equiloading, for its graphical representation is not an oriented multicycle. The transition function δ is defined by

$$\delta(q_0, a) = q_0, \quad \delta(q_0, b) = q_1, \quad \delta(q_1, b) = q_1.$$

We will show that the expression $|\#[q_0, L \cap \Sigma^n] - \#[q_1, L \cap \Sigma^n]|$ is bounded from above by $n+1 = |L \cap \Sigma^n|$. The load of the state q_0 is $\sum_{i=0}^n i+1$, because $\#[q_0, a^i b^{n-i}] = i+1$.

The load of the state q_1 is $\sum_{i=0}^n n - i = \sum_{i=0}^n i$. Therefore,

$$|\#[q_0, L \cap \Sigma^n]| - |\#[q_1, L \cap \Sigma^n]| = \sum_{i=0}^n (i + 1 - i) = \sum_{i=0}^n 1 = n + 1.$$

Hence, A is equiloader and $L \in \mathcal{L}_{\text{EQA}}$.

To show that $\mathcal{L}_{\text{EQA}} \subsetneq \mathcal{R}$ it suffices to find a language L and its minimal-state automaton B such that, for any ℓ , there exists arbitrarily large n such that B uses a particular state more than ℓ times the load of another state on words of the length n . This statement is proved in Theorem 4.3.* Such a language is for example the language $L = \{wbbv \mid w, v \in \Sigma^*\}$ with the minimal-state automaton B shown in Figure 4.2.

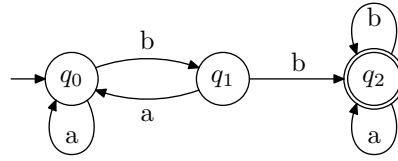


Figure 4.2: The minimal-state automaton B for the language $L = \{ubbv \mid u, v \in \Sigma^*\}$

For a given length n , words from $L(A)$ are of the form $a^{i_1}ba^{i_2}b \dots a^{i_m}bbv$, where $|v| = n - m - 1 - \sum_{j=0}^m i_j$. The load of q_2 on these words is equal to $|v| + 1$. Therefore,

$$\#[q_2, L \cap \Sigma^n] = \sum_{i=0}^{n-2} 2^i \sum_{m>0} \binom{n-i-2-m}{m} (i+1).$$

Similarly the load of q_1 on the words of above form is equal to m , so it holds that

$$\#[q_1, L \cap \Sigma^n] = \sum_{i=0}^{n-2} 2^i \sum_{m>0} \binom{n-i-2-m}{m} (m+1).$$

From the fact that

$$\sum_{m>0} \binom{n-i-2-m}{m} = F_{n-i-1},$$

where F_n is the n -th Fibonacci number, we obtain

$$\#[q_2, L \cap \Sigma^n] = \sum_{i=0}^{n-2} 2^i (i+1) F_{n-i-1},$$

and

$$\#[q_1, L \cap \Sigma^n] \leq \sum_{i=0}^{n-2} 2^i \sum_{m>0} \binom{n-i-2-m}{m} (n-i-2) = \sum_{i=0}^{n-2} 2^i (n-i-2) F_{n-i-1}.$$

It is a well known fact that there are constants a, b such that $a\phi^n < F_n < b\phi^n$, where

*Theorem 4.3 is proved independently of the result $\mathcal{L}_{\text{EQA}} \subsetneq \mathcal{R}$.

ϕ is the golden ratio. From that we can compute a lower bound of $\#[q_2, L \cap \Sigma^n]$ as

$$\#[q_2, L \cap \Sigma^n] \geq \sum_{i=0}^{n-2} 2^i(i+1)a\phi^n - i - 2 = a\phi^{n-2} \cdot \sum_{i=0}^{n-2} (i+1) \left(\frac{2}{\phi}\right)^i.$$

By simplifying the sum we obtain

$$\#[q_2, L \cap \Sigma^n] \geq c_2\phi^{n-2}(n-2) \left(\frac{2}{\phi}\right)^{n-1}.$$

The analogous computation can be done for the load of the state q_1 :

$$\begin{aligned} \#[q_1, L \cap \Sigma^n] &\leq b\phi^{n-2} \sum_{i=0}^{n-2} (n-i-2) \left(\frac{2}{\phi}\right)^i \\ &\leq b\phi^{n-2} \sum_{j=0}^{n-3} \sum_{i=0}^j \left(\frac{2}{\phi}\right)^i \\ &\leq \frac{b}{\left(\frac{2}{\phi} - 1\right)} \phi^{n-2} \sum_{j=0}^{n-3} \left(\frac{2}{\phi}\right)^j \\ &\leq c_1\phi^{n-2} \left(\frac{2}{\phi}\right)^{n-2} \leq c_1\phi^{n-2} \left(\frac{2}{\phi}\right)^{n-1}. \end{aligned}$$

From above we get that $\#[q_2, L \cap \Sigma^n] > ((n-2)c_2/c_1) \cdot \#[q_1, L \cap \Sigma^n]$, therefore for any ℓ from Theorem 4.3 there exists an arbitrarily large number n such that

$$\#[q_2, L \cap \Sigma^n] > \ell \#[q_1, L \cap \Sigma^n].$$

Hence, B is not equiloading and $\mathcal{L}_{\text{EQA}} \neq \mathcal{R}$. □

Corollary 4.1. Every finite language is in \mathcal{L}_{EQA} .

Proof. Follows directly from Theorem 4.1. □

4.3 Relationship with Minimal-State Automaton

Unlike in the case of strict equiloadingness, there is a language $L \in \mathcal{L}_{\text{EQA}}$ such that the minimal-state automaton for L is not equiloading. Therefore, it is harder to show that some language L does not belong to \mathcal{L}_{EQA} because it does not suffice to prove that the minimal-state automaton is not equiloading. However, there is a relationship between minimal-state automaton and equiloadingness of a language, as we shall see in Theorem 4.3

Theorem 4.2. There exists a language $L \in \mathcal{L}_{\text{EQA}}$ such that the minimal-state automaton for the language L is not equiloading.

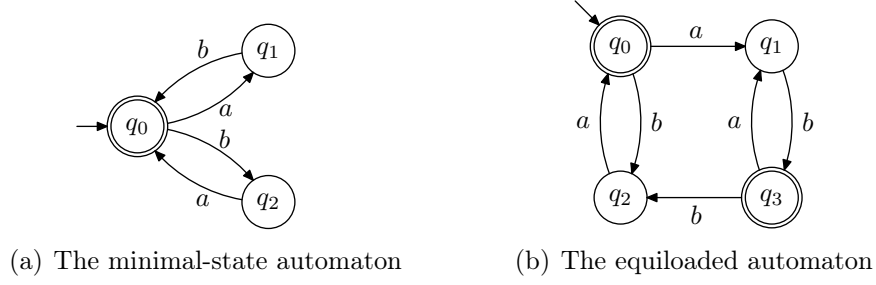


Figure 4.3: The minimal-state automaton and the equiloading automaton for the language $L = \{ab, ba\}^*$

Proof. Consider the language $L = \{ab, ba\}^*$. The minimal state automaton in Figure 4.3(a) for L is $A_1 = (\{q_0, q_1, q_2\}, \{a, b\}, \delta_1, q_0, \{q_0\})$, where δ_1 is defined by

$$\begin{aligned} \delta_1(q_0, a) &= q_1, & \delta_1(q_0, b) &= q_2, \\ \delta_1(q_1, b) &= q_0, & \delta_1(q_2, a) &= q_0. \end{aligned}$$

We can see that A_1 is not equiloading, because

$$\begin{aligned} \sum_{w \in L \cap \Sigma^{2n}} \#[q_0, w] &= (n+1) \cdot 2^n, \\ \frac{(2n+1) \cdot 2^n}{3} &= \frac{2n+1}{3} \cdot 2^n, \end{aligned}$$

and from this and Lemma 4.1 we get $k \geq (n-2)/3$, so k is not a constant.

Now it suffices to show that $L \in \mathcal{L}_{\text{EQA}}$. In order to find an equiloading automaton for L , we can look at the automaton A_1 and determine that q_0 is used every time q_1 or q_2 is used. So we can try to split the state q_0 into two states. We obtain an automaton in Figure 4.3(b) $A_2 = (\{q_0, q_1, q_2, q_3\}, \{a, b\}, \delta_2, q_0, \{q_0, q_3\})$, where δ_2 is defined by

$$\begin{aligned} \delta_2(q_0, a) &= q_1, & \delta_2(q_0, b) &= q_2, & \delta_2(q_1, b) &= q_3, \\ \delta_2(q_2, a) &= q_0, & \delta_2(q_3, a) &= q_1, & \delta_2(q_3, b) &= q_2. \end{aligned}$$

This automaton is equiloading. One way to prove this is by using algebraic representation from Section 4.7. Another way is to directly use the definition, or the equivalent form from Lemma 4.1. It is easy to see that the most used state will be q_0 or q_3 because it holds that $\#[q_0, w] \geq \#[q_2, w]$ and $\#[q_3, w] \geq \#[q_1, w]$. It is easy to see that, for a word w consisting of i pairs “ab” and j pairs “ba”, the load of q_0 is $\#[q_0, w] = j+1$ and the load of q_1 is $\#[q_3, w] = i$. Therefore, it holds that

$$\begin{aligned} \#[q_0, L \cup \Sigma^{2n}] &= \sum_{i=0}^n \binom{n}{i} (i+1) = 2^{n-1}(n+2) \\ \#[q_3, L \cup \Sigma^{2n}] &= \sum_{i=0}^n \binom{n}{i} (i) = 2^{n-1}n. \end{aligned}$$

The most used state is q_0 . The average load of states is $(2n+1)2^{n-2}$, therefore there exists k such that

$$2^{n-1}(n+2) - (2n+1)2^{n-2} = 3 \cdot 2^{n-2} \leq k|L \cap \Sigma^{2n}| = k2^n.$$

Thus A_2 is equiloading and $L \in \mathcal{L}_{\text{EQA}}$. \square

Theorem 4.3. Let L be a language. If for the minimal-state automaton A for the language L it holds that

$$\exists p, q \in Q \ \forall \ell \in \mathbb{R}^+ \ \forall n_0 \in \mathbb{N} \ \exists n \in \mathbb{N}, \ n \geq n_0 \quad \# [p, L \cap \Sigma^n] > \ell \# [q, L \cap \Sigma^n],$$

then $L \notin \mathcal{L}_{\text{EQA}}$.

Proof. Suppose that $L \in \mathcal{L}_{\text{EQA}}$ and let $B = (Q_B, \Sigma, \delta_B, q_{0B}, F_B)$ be an arbitrary equiloading automaton such that $L = L(B)$. Let k_B be the equiloading constant of B . From the condition in the theorem, there are states p, q such that the inequality holds. Some of states from Q_B (let us call them p_1, \dots, p_c) compose the equivalence class from Myhill-Nerode Theorem, which belongs to the state p . Similarly, there are some states q_1, \dots, q_d , which belong to the state q . At least for one of the states p_1, \dots, p_c (let it be p_1) it holds

$$\#_B[p_1, L \cap \Sigma^n] \geq \frac{\#_A[p, L \cap \Sigma^n]}{c}.$$

Similarly, without loss of generality, suppose that for q_1 it holds

$$\#_B[q_1, L \cap \Sigma^n] \leq \frac{\#_A[q, L \cap \Sigma^n]}{d}.$$

Let $\ell = (k_B + 1)c$. Then

$$\# [p_1, L \cap \Sigma^n] \geq \frac{\# [p, L \cap \Sigma^n]}{c} > \frac{(k_B + 1)d \# [q, L \cap \Sigma^n]}{d} \geq (k_B + 1)d \# [q_1, L \cap \Sigma^n].$$

From the above inequality we have

$$\# [p_1, L \cap \Sigma^n] - \# [q_1, L \cap \Sigma^n] > k_B d \# [q_1, L \cap \Sigma^n].$$

If $\# [q_1, L \cap \Sigma^n] > |L \cap \Sigma^n|/d$, it is clear that B cannot be equiloading, thus we can assume the contrary. But then $\# [q_1, L \cap \Sigma^n] \leq |L \cap \Sigma^n|/d$ and there is some state, that is used more or equal to the average load of all states, thus

$$\frac{(n+1)|L \cap \Sigma^n|}{|Q|} - |L \cap \Sigma^n| = \frac{(n+1 - |Q|)|L \cap \Sigma^n|}{|Q|},$$

so B is not equiloading. Therefore, our first assumption $L \in \mathcal{L}_{\text{EQA}}$ must be false. \square

4.4 Automata Transformations

Theorem 4.4. Let A be a DFA. Let B be a DFA, obtained from A by a sequence of arbitrary changes in the transition function from $\delta(p, x) = q$ to $\delta(p, y) = q$ in such a way that B is still a deterministic finite automaton. If A is equiloading, then B is equiloading.

Proof. The graphical representation of the automaton A is equal to the graphical representation of the automaton B . Thus, for every word $w \in L(A)$ there is exactly one word $w' \in L(B)$ such that B uses the same sequence of transitions on w' as A uses on w . A load of a particular state q in the automaton A on a word w will be the same as the load of q in the automaton B on a word w' . Therefore $\#_A[q, L(A) \cap \Sigma^n] = \#_B[q, L(B) \cap \Sigma^n]$, so B is equiloading. \square

Definition 4.2. Let $A = (Q_A, \Sigma_A, \delta_A, q_{0A}, F_A)$, $B = (Q_B, \Sigma_B, \delta_B, q_{0B}, F_B)$ be deterministic finite automata such that $\Sigma_A \cap \Sigma_B = \emptyset$. The A, B -composition automaton $C = (Q_A \times Q_B, \Sigma_A \cup \Sigma_B, \delta_C, (q_{0A}, q_{0B}), F_A \times F_B)$ is a DFA with δ_C such that

$$\begin{aligned} \forall x \in \Sigma_B \quad \delta_C((q_A, q_B), x) &= (q_A, p_B) \stackrel{\text{def}}{\iff} \delta_B(q_B, x) = p_B, \\ \forall x \in \Sigma_A \quad \delta_C((q_A, q_B), x) &= (p_A, q_{0B}) \stackrel{\text{def}}{\iff} \delta_A(q_A, x) = p_A \text{ and } q_B \in F_B. \end{aligned}$$

We shall write $C = A \circ B$.

Example 4.2. Let A be a minimal-state automaton for a language $L_1 = \{a^{3n+2} \mid n \in \mathbb{N}\}$ and let B be a minimal-state automaton for $L_2 = (\{b\} \cdot \{b, cc\})^* \cdot \{b\}$. (See figure 4.4.) Then automaton $C = A \circ B$ is an automaton that accepts a language

$$L_3 = \{w_1 a w_2 \dots a w_{3n} \mid n \in \mathbb{N}, \forall i \leq 3n \ w_i \in L_2\}.$$

Theorem 4.5. Let $A = (Q_A, \Sigma_A, \delta_A, q_{0A}, F_A)$, $B = (Q_B, \Sigma_B, \delta_B, q_{0B}, F_B)$ be equiloading automata such that $\Sigma_A \cap \Sigma_B = \emptyset$, and the equiloading constants for both A and B are equal to 0. Then the automaton $A \circ B$ is equiloading with equiloading constant 0.

Proof. We compute the load of each state while the automaton $C = A \circ B$ processes all words of length n . It can be shown that a word $w \in L(C) = L$ of the length n has the form $w = w_1 a_1 w_2 a_2 \dots w_k$, where $w_i \in L(B)$, $a_1 a_2 \dots a_{n-1} \in L(A)$. We denote $L \cap \Sigma^n$ by $L^{(n)}$. We shall show that

$$\begin{aligned} |\#_C[(p, q_1), L^{(n)}] - \#_C[(p, q_2), L^{(n)}]| &\leq 0 \text{ and} \\ |\#_C[(p_1, q), L^{(n)}] - \#_C[(p_2, q), L^{(n)}]| &\leq 0. \end{aligned}$$

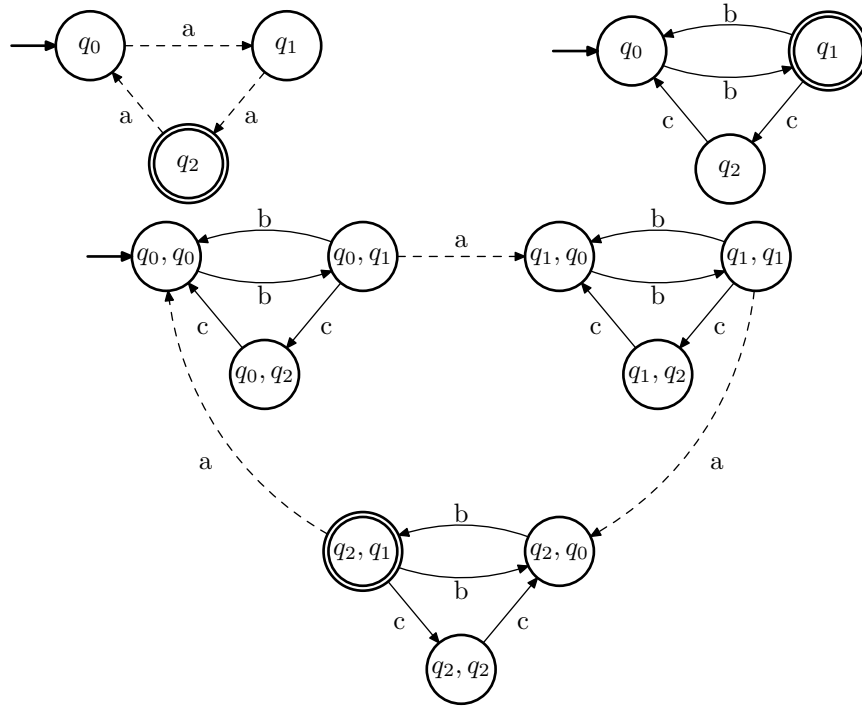


Figure 4.4: The automata A (left) and B (right) compose the automaton $C = A \circ B$ (below).

Then it holds that

$$\begin{aligned}
 & |\#_C[(p_1, q_1), L^{(n)}] - \#_C[(p_2, q_2), L^{(n)}]| \\
 = & |\#_C[(p_1, q_1), L^{(n)}] - \#_C[(p_1, q_2), L^{(n)}] + \#_C[(p_1, q_2), L^{(n)}] - \#_C[(p_2, q_2), L^{(n)}]| \\
 \leq & |\#_C[(p_1, q_1), L^{(n)}] - \#_C[(p_1, q_2), L^{(n)}]| + |\#_C[(p_1, q_2), L^{(n)}] - \#_C[(p_2, q_2), L^{(n)}]| \\
 \leq & 0,
 \end{aligned}$$

and $A \circ B$ is equiloading.

It is clear from the construction of $A \circ B$ that

$$L(A \circ B) = \{w_1 a_1 w_2 \dots a_{n-1} w_n \mid w_i \in L(B), a_1 a_2 \dots a_n \in L(A)\}.$$

Therefore, for all words of a given length n , it holds that

$$L^{(n)} = \bigcup_{i=0}^n L_i^{(n)},$$

where

$$L_i^{(n)} = \{w_1 a_1 \dots a_i w_{i+1} \mid w_k \in L(B), a_1 \dots a_i \in L(A), \sum_{k=1}^{i+1} |w_k| = n - i\}.$$

Firstly, we shall compute $|L^{(n)}|$. It holds that

$$|L^{(n)}| = \sum_{i=0}^n |L_i^{(n)}| = \sum_{i=0}^n |L(A)^{(i)}| \cdot \sum_{j=0}^{n-i} \binom{n-j-1}{i-1} (i+1) |L(B)^{(j)}|,$$

because for given a_1, \dots, a_i , there are $(n-j-1)$ choose $(i-1)$ words in $L^{(i)}$ such that the first substring from $L(B)$ has the length j .

Now we shall compute $\#[(p, q), L^{(n)}]$ by summing the load of (p, q) on all words from $L_i^{(n)}$. Similarly as in the case of counting words from $L_i^{(n)}$ it holds that

$$\begin{aligned} \#[(p, q), L^{(n)}] &= \sum_{i=0}^n \# [p, L(A)^{(i)}] \cdot \sum_{j=0}^{n-i} \binom{n-j-1}{i-1} (i+1) \# [q, L(B)^{(j)}] \\ &= \sum_{i=0}^n \frac{(i+1) |L(A)^{(i)}|}{|Q_A|} \cdot \sum_{j=0}^{n-i} \binom{n-j-1}{i-1} (i+1) \frac{(j+1) |L(B)^{(j)}|}{|Q_B|}. \end{aligned}$$

In the above equation we can see that the load of a state (p, q) does not depend on p or q , therefore the load is the same for (p, q) and (p, q') , or for (p, q) and (p', q) . It means that any two states are equally loaded on words from $L^{(n)}$, therefore equiloadingness constant for C is equal to 0. \square

The previous theorem does not hold if the equiloadingness constant for A or B is non-zero.

Theorem 4.6. Let Σ_A, Σ_B be finite alphabets such that $\Sigma_A \cap \Sigma_B = \emptyset$. There exist equiloading automata $A = (Q_A, \Sigma_A, \delta_A, q_{0A}, F_A)$, $B = (Q_B, \Sigma_B, \delta_B, q_{0B}, F_B)$ such that $A \circ B$ is not equiloading.

Proof. Let A be an automaton for the language $L_A = \{a, b\}$ and B be the minimal-state automaton for the language $L_B = \{c^i \mid i \in \mathbb{N}\}$. A language accepted by $A \circ B$ is the language $L = \{c^i x c^j \mid i, j \in \mathbb{N}, x \in \{a, b\}\}$. The automaton $A \circ B$ is not equiloading, although the language $L \in \mathcal{L}_{\text{EQA}}$. The load of the state (q_{0A}, q_{0B}) is

$$\#[(q_{0A}, q_{0B}), L \cap \Sigma^n] = 2 \sum_{i=0}^{n-1} i + 1 = n(n+1).$$

The average load of the states of $A \circ B$ is $(n+1)n/3$. Thus, there is no constant k such that

$$n(n+1) - \frac{n(n+1)}{3} = \frac{2n(n+1)}{3} \leq k(n).$$

\square

4.5 Closure Properties of \mathcal{L}_{EQA}

In this section we shall prove several theorems about closure properties of the family \mathcal{L}_{EQA} . Most of them are proved using Theorem 4.3.

Theorem 4.7. The family \mathcal{L}_{EQA} is not closed under union.

Proof. Consider languages $L_a = \{a^i \mid i \in \mathbb{N}\}$ and $L_b = \{b^i \mid i \in \mathbb{N}\}$. It is clear that $L_a, L_b \in \mathcal{L}_{\text{EQA}}$. In an automaton A which accepts $L = L_a \cup L_b$, there must be an initial state q_0 such that automaton A will not return to q_0 during computation. Therefore, the load of q_0 on words of a given length n is equal to the number of words of the length n . (Which is equal to 2: a^n and b^n .) Moreover, there is a state $q \in Q_A$ such that

$$\#[q, L \cap \Sigma^n] \geq \frac{(n+1)|L \cap \Sigma^n|}{|Q_A|} = \frac{2(n+1)}{|Q_A|}.$$

From the above we get

$$\#[q, L \cap \Sigma^n] - \#[q_0, L \cap \Sigma^n] \geq \frac{2(n+1)}{|Q_A|} - 2 = \left(\frac{n+1}{|Q_A|} - 1 \right) |L \cap \Sigma^n|,$$

thus, A is not equiloading. □

Theorem 4.8. The family \mathcal{L}_{EQA} is not closed under homomorphism.

Proof. Let $L = \{a^i b a^j \mid i, j \in \mathbb{N}\}$. This language is in the family \mathcal{L}_{EQA} , we can construct the automaton for the L by relabelling one arc in the graphical representation of the minimal state automaton for the language $L_1 = \{a^i b^j \mid i, j \in \mathbb{N}, j \neq 0\}$. (We relabel the loop (q_1, q_1) by a .) Let h be a homomorphism such that $h(a) = a$, $h(b) = bb$. Then the minimal-state automaton $A = (\{q_0, q_1, q_2\}, \{a, b\}, \delta_A, q_0, \{q_2\})$ for the language $h(L) = \{a^i b b a^j \mid i, j \in \mathbb{N}\}$ fulfils the condition from Theorem 4.3, so $h(L) \notin \mathcal{L}_{\text{EQA}}$. (The transition function δ_A is defined by $\delta_A(q_0, a) = q_0$, $\delta_A(q_0, b) = q_1$, $\delta_A(q_1, a) = q_1$). For showing it we compare the load of states q_1 and q_2 in the automaton A .

On the word $a^i b b a^j \in h(L)$ the state q_1 is used once, and the state q_2 is used $j+1$ times. Because each word is determined by position of the first occurrence of the symbol b , the number of words of a given length n is n . Therefore, we obtain

$$\#[q_2, h(L) \cap \Sigma^n] = \sum_{i=0}^{n-1} (n-i) = \frac{n^2 + n}{2},$$

and

$$\#[q_1, h(L) \cap \Sigma^n] = \sum_{i=0}^{n-1} 1 = n.$$

Thus, for any ℓ there exists arbitrarily large n such that the load of the state q_2 is at least ℓ times greater than the load of the state q_1 . This ensures that we can use Theorem 4.3, hence $h(L) \notin \mathcal{L}_{\text{EQA}}$. □

Theorem 4.9. The family \mathcal{L}_{EQA} is not closed under concatenation.

Proof. Consider languages $L_1 = \{a^i \mid i \in \mathbb{N}\}$ and $L_2 = \{b\}$. They both belong to the family \mathcal{L}_{EQA} , for the first the minimal-state automaton is equiloading, the second is finite thus belongs to $\mathcal{L}_{\text{SEQA}} \subseteq \mathcal{L}_{\text{EQA}}$. We will show that the concatenation of these languages $L = L_1 \cdot L_2 = \{a^i b \mid i \in \mathbb{N}\}$ is not in the family \mathcal{L}_{EQA} , because for the minimal-state automaton $A = (\{q_0, q_1\}, \Sigma, \delta, q_0, \{q_1\})$ the condition from Theorem 4.3 holds: $(L \cap \Sigma^n = \{a^{n-1}b\})$

$$\#[q_0, L \cap \Sigma^n] = n, \quad \#[q_1, L \cap \Sigma^n] = 1,$$

so for a number ℓ there is a length $n = \ell + 1$ such that the load of q_0 is greater than ℓ times the load of q_1 . \square

Theorem 4.10. The family \mathcal{L}_{EQA} is not closed under intersection.

Proof. As we showed in the proof of Theorem 4.11, the deterministic finite automaton $A = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_2\})$, where the transition function is defined by

$$\begin{aligned} \delta(q_0, a) &= q_0, & \delta(q_0, b) &= q_1, & \delta(q_1, c) &= q_1, \\ \delta(q_1, b) &= q_2, & \delta(q_2, a) &= q_2, \end{aligned}$$

is equiloading. It is easy to see that the language accepted by the automaton A is $L = \{a^i b c^j b a^k \mid i, j, k \in \mathbb{N}\}$. By relabeling the loop (q_1, q_1) by d we obtain equiloading automaton A' for the language $L' = \{a^i b d^j b a^k \mid i, j, k \in \mathbb{N}\}$. The intersection of L and L' is $L_1 \cap L_2 = \{a^i b b a^k \mid i, k \in \mathbb{N}\}$. This language is not equiloading, as was shown in the proof of Theorem 4.8. Hence, the family \mathcal{L}_{EQA} is not closed under intersection. \square

Theorem 4.11. The family \mathcal{L}_{EQA} is not closed under inverse homomorphism.

Proof. Consider a language $L = \{a^i b c^j b a^k \mid i, j, k \in \mathbb{N}\}$ and homomorphism h such that $h(a) = a$, $h(b) = b$, $h(c) = a$. Then $L' = h^{-1}(L) = \{a^i b b a^j \mid i, j \in \mathbb{N}\}$. We already know from the proof of Theorem 4.8 that $L' \notin \mathcal{L}_{\text{EQA}}$. We will show that $L \in \mathcal{L}_{\text{EQA}}$. Consider the minimal-state automaton $A = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_2\})$ for language L , where the transition function is defined by

$$\begin{aligned} \delta(q_0, a) &= q_0, & \delta(q_0, b) &= q_1, & \delta(q_1, c) &= q_1, \\ \delta(q_1, b) &= q_2, & \delta(q_2, a) &= q_2. \end{aligned}$$

Consider a word $a^i b c^j b a^k$ of length n . On this word, the load of the state q_0 is equal to $i + 1$, the load of the state q_1 is equal to $j + 1$, and the load of the state q_2 is equal to $k + 1 = n - i - j - 1$. The number of words of length n is equal to $(n^2 + n - 2)/2$

Let us compute the load on words from $L \cap \Sigma^n$:

$$\begin{aligned}
\#[q_0, L \cap \Sigma^n] &= \sum_{i=0}^{n-2} \sum_{j=0}^{n-i-1} i + 1 = \sum_{i=0}^{n-2} (i+1)(n-i) \\
&= (n-1) \left(\frac{(n-1)(n-2)}{2} \right) + n(n-1) - \frac{(n-2)(n-1)(2n-3)}{6} \\
&= \frac{n(n-1)(n+4)}{6} = \frac{n^3 + 3n^2 - 4n}{2}, \\
\#[q_1, L \cap \Sigma^n] &= \sum_{i=0}^{n-2} \sum_{j=0}^{n-i-1} j + 1 = \sum_{i=0}^{n-2} \frac{(n-i)(n-i+1)}{2} \\
&= \frac{(n-1)(n^2 + 4n + 6)}{6} = \frac{n^3 + 3n^2 + 2n - 6}{6}, \\
\#[q_2, L \cap \Sigma^n] &= \sum_{i=0}^{n-2} \sum_{j=0}^{n-i-1} n - i - j - 1 = \sum_{i=0}^{n-2} \frac{(n-i)(n-i-1)}{6} \\
&= \frac{(n-1)n(n+1)}{6} = \frac{n^3 - n}{6}.
\end{aligned}$$

Hence we have

$$\begin{aligned}
|\#[p, L \cap \Sigma^n] - \#[q, L \cap \Sigma^n]| &\leq \frac{(n^3 + 3n^2 + 2n - 6) - (n^3 - n)}{6} \\
&= \frac{3n^2 + 3n - 6}{6} = |L \cap \Sigma^n|.
\end{aligned}$$

Thus A is equiloading, $L \in \mathcal{L}_{\text{EQA}}$, $h^{-1}(L) = L' \notin \mathcal{L}_{\text{EQA}}$, hence the family \mathcal{L}_{EQA} is not closed under inverse homomorphism. \square

Theorem 4.12. The family \mathcal{L}_{EQA} is not closed under reversal.

Proof. Consider the language $L = \{a^i b^j \mid i, j \in \mathbb{N}\}$. We will show that $L \in \mathcal{L}_{\text{EQA}}$, but $L^C \notin \mathcal{L}_{\text{EQA}}$. The minimal-state automaton $A = (\{q_0, q_1\}, \Sigma, \delta_A, q_0, \{q_0, q_1\})$ for the language L , where the transition function is defined by

$$\delta_A(q_0, a) = q_0, \quad \delta_A(q_0, b) = q_1, \quad \delta_A(q_1, b) = q_1,$$

is equiloading. To see it, let us compute the load of state q_0 and q_1 respectively.

$$\begin{aligned}
\#[q_0, L \cap \Sigma^n] &= \sum_{i=0}^{n-1} i + 1 = \frac{i^2 + i}{2}, \\
\#[q_1, L \cap \Sigma^n] &= \sum_{i=0}^{n-1} n - i = \frac{i^2 + i}{2}.
\end{aligned}$$

It means that A is equiloading with the equiloading constant equal to 0.

The minimal-state automaton $B = (\{q_0, q_1, q_2\}, \Sigma, \delta_B, q_0, \{q_1, q_2\})$ for language L^R

has the transition function defined by

$$\delta_B(q_0, b) = q_1, \quad \delta_B(q_1, b) = q_1, \quad \delta_B(q_1, a) = q_2, \quad \delta_B(q_2, a) = q_2.$$

It is obvious that the state q_0 is used exactly once on every word, thus $|L \cap \Sigma^n|$ times on all words of a given length n . For length n there exists a state q used at least $(n+1)|L \cap \Sigma^n|/3$ times. This means that for any ℓ there is an arbitrary big n such that $\#[q, L \cap \Sigma^n]$ is greater than $\ell \cdot \#[q_0, L \cap \Sigma^n]$. Therefore by Theorem 4.3 $L^R \notin \mathcal{L}_{\text{EQA}}$ and thus \mathcal{L}_{EQA} is not closed under reversal. \square

Theorem 4.13. The family \mathcal{L}_{EQA} is not closed under complement.

Proof. Every finite language belongs to the family \mathcal{L}_{EQA} , so does $L = \{aa\} \in \mathcal{L}_{\text{EQA}}$. We will show that the minimal-state automaton $A = (\{q_0, \dots, q_3\}, \{a, b\}, \delta, q_0, \{q_0, q_1, q_3\})$ shown in Figure 4.5 fulfils the condition from Theorem 4.3. On every word w the state q_0 is used only once and the state q_3 is used at least $|w| - 2$ times. Therefore, it is easy to see that for any ℓ there exists arbitrarily large n ($n > \ell + 3$) such that the load of the state q_2 is greater than ℓ times the load of the state q_0 . The language L^R is not in the family \mathcal{L}_{EQA} , thus \mathcal{L}_{EQA} is not closed under complement. \square

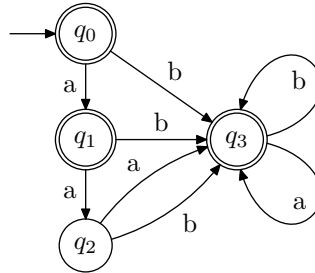


Figure 4.5: The minimal-state automaton for the language $\{a, b\}^* - \{aa\}$.

We left open the problem of determining whether the family $\mathcal{L}_{\text{SEQA}}$ is closed under Kleene star and Kleene plus, we believe that the answer is negative in both cases. The reader can compare our results with closure properties of the family of regular languages in Table 4.1.

	\cup	\cap	\cdot	h	h^{-1}	C	R	$*$	$+$
\mathcal{R}	yes	yes	yes	yes	yes	yes	yes	yes	yes
\mathcal{L}_{EQA}	no	no	no	no	no	no	no	open	open
$\mathcal{L}_{\text{SEQA}}$	no	yes	no	no	no	no	no	no	no

Table 4.1: Closure properties of \mathcal{R} , \mathcal{L}_{EQA} and $\mathcal{L}_{\text{SEQA}}$

4.6 Characterization

Since it is not true that $L \in \mathcal{L}_{\text{EQA}}$ if and only if the minimal-state automaton for L is equiloading, it is harder to characterize the family \mathcal{L}_{EQA} . In this section, we present our approaches to the characterization of the family \mathcal{L}_{EQA} , although we will not prove this characterization. We shall state some theorems that partially characterize this family, but a final characterization is still open.

The characterization of the family $\mathcal{L}_{\text{SEQA}}$ was built on the graphical representation of automata regardless of a set of accepting states F . However, in the case of the family \mathcal{L}_{EQA} we shall see that graphical representation of automata alone does not suffice.

There are two ways to create a partial characterization. One way is to formulate a condition such that if it holds for an automaton A , then A is not equiloading (or, conversely, if A is equiloading, then condition is not true). A good candidate for this condition seems to be a bridge in the graphical representation of an automaton, but as the theorem below demonstrates, this condition is not really good for our purposes.

Theorem 4.14. There is an equiloading automaton A such that the graphical representation of A contains a bridge.

Proof. Such an automaton is, for example, any automaton for a finite language, or the minimal-state automaton for the language $L = \{a^i b^j \mid i, j \in \mathbb{N}\}$ considered in the proof of Theorem 4.1. \square

Another type of condition which will partially characterize the family $\mathcal{L}_{\text{SEQA}}$ is such a condition that if it holds, then A is equiloading. A good candidate for this type of condition seems to be “equal number of cycles through each state.” But, unfortunately, this is not a sufficient condition.

Theorem 4.15. There is a non-equiloading automaton A such that there is an equal number of cycles through each state.

Proof. Consider the minimal-state automaton $A = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_1\})$ for the language $L = \{a^i b^{2j+1} \mid i, j \in \mathbb{N}\}$ that has one cycle through the state q_0 and one cycle through the states q_1, q_2 . Therefore, there is an equal number of cycles through all states. This automaton is not equiloading. \square

4.7 Algebraic Representation

We shall now introduce an algebraic representation for DFA. This representation can be used to show (non-)equiloadingness of automata.

Let $A = (Q, \Sigma, \delta, q_0, F)$ be a DFA. For $n \in \mathbb{N}$, we shall use

$$M_n = \begin{pmatrix} m_{0,0}^n & m_{0,1}^n & \cdots & m_{0,|Q|-1}^n \\ m_{1,0}^n & m_{1,1}^n & \cdots & m_{1,|Q|-1}^n \\ \vdots & \vdots & \ddots & \vdots \\ m_{|Q|-1,0}^n & m_{|Q|-1,1}^n & \cdots & m_{|Q|-1,|Q|-1}^n \end{pmatrix}, \quad \alpha_n = \begin{pmatrix} \alpha_0^n \\ \alpha_1^n \\ \vdots \\ \alpha_{|Q|-1}^n \end{pmatrix},$$

where M_n is a matrix (of the size $|Q| \times |Q|$) where the element $m_{i,j}^n$ equals to the load of the state q_j at all words of length n , for which the computation of A finishes in the state q_i . The α_n is a column vector such that α_i^n is the number of words of length n , for which A 's computation finishes in the state q_i .

Without loss of generality, for $n = 0$ it holds that

$$M_0 = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}, \quad \alpha_0 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}.$$

If we want to compute M_n from M_{n-1} (and α_{n-1}), we need a transition matrix Δ from the transition function of A . The element $\delta_{i,j}$ is the number of transitions from q_j to q_i . (For a better insight see the proof of Theorem 4.16.) Now we can create formulae for both α_n and M_n :

$$\alpha_n = \Delta \cdot \alpha_{n-1}, \quad (4.2)$$

$$M_n = \Delta \cdot M_{n-1} + \text{diag}(\alpha_n). \quad (4.3)$$

Remark. The function *diag* is defined by

$$\text{diag} \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_k \end{pmatrix} = \begin{pmatrix} a_0 & 0 & \cdots & 0 \\ 0 & a_1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_k \end{pmatrix}.$$

If we are able to compute the matrix M_n , we can easily compute the minimal value of the constant k from Definition 4.1 such that the condition from this definition holds for n . We can construct a vector φ with 1 at the i -th element if q_i is an accepting state and 0 otherwise. By multiplying φ and M_n we obtain a vector ψ with the load of the state q_i at the i -th element of the vector ψ (on words from $L(A)$ of length n). The maximal element of ψ contains the load of the maximally used state. We can compute the average load by summing all elements of ψ and dividing by $|Q|$.

Now we will show an example of proving the equiloadingness of an automaton using the algebraic representation.

Theorem 4.16. An automaton $A = (\{q_0, q_1, q_2, q_3\}, \{a, b\}, \delta, q_0, \{q_0, q_3\})$, where δ is defined by

$$\begin{aligned} \delta(q_0, a) &= q_1, & \delta(q_0, b) &= q_3, & \delta(q_1, b) &= q_2, \\ \delta(q_3, a) &= q_0, & \delta(q_2, a) &= q_1, & \delta(q_2, b) &= q_3. \end{aligned}$$

is equiloading.

Proof. We shall prove the equiloadingness of the automaton A using algebraic representation. The transition matrix Δ for the automaton A is

$$\Delta = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}.$$

Now we prove that for $n > 0$ it holds that

$$\alpha_{2n} = \begin{pmatrix} 2^{n-1} \\ 0 \\ 2^{n-1} \\ 0 \end{pmatrix}, \quad \text{and} \quad \alpha_{2n+1} = \begin{pmatrix} 0 \\ 2^{n-1} \\ 0 \\ 2^{n-1} \end{pmatrix}. \quad (4.4)$$

We can easily see that the previous statement holds for $n = 1$. By induction we obtain

$$\alpha_{2n+2} = \Delta \alpha_{2n+1} = \begin{pmatrix} 2^n \\ 0 \\ 2^n \\ 0 \end{pmatrix}, \quad \alpha_{2n+3} = \Delta \alpha_{2n+2} = \begin{pmatrix} 0 \\ 2^n \\ 0 \\ 2^n \end{pmatrix}.$$

Next we shall look at M_0, \dots, M_4 and we see that

$$\begin{aligned} M_0 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, & M_1 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}, & M_2 &= \begin{pmatrix} 2 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ M_3 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 3 & 3 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 3 & 1 & 1 & 3 \end{pmatrix}, & M_4 &= \begin{pmatrix} 5 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 3 & 3 & 3 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}. \end{aligned}$$

Using (4.4) we can see that if M_{2n} (as M_4 is) can be written (for some value c_n) as

$$M_{2n} = \begin{pmatrix} c_n + 2^{n-1} & c_n - 2^{n-1} & c_n - 2^{n-1} & c_n \\ 0 & 0 & 0 & 0 \\ c_n & c_n & c_n & c_n - 2^{n-1} \\ 0 & 0 & 0 & 0 \end{pmatrix},$$

then the matrix M_{2n+2} can be written as

$$\begin{aligned}
 M_{2n+2} &= \begin{pmatrix} 2c_n + 2^n + 2^{n-1} & 2c_n - 2^{n-1} & 2c_n - 2^{n-1} & 2c_n + 2^{n-1} \\ 0 & 0 & 0 & 0 \\ 2c_n + 2^{n-1} & 2c_n + 2^{n-1} & 2c_n + 2^{n-1} & 2c_n - 2^{n-1} \\ 0 & 0 & 0 & 0 \end{pmatrix} \\
 &= \begin{pmatrix} c_{n+1} + 2^n & c_{n+1} - 2^n & c_{n+1} - 2^n & c_{n+1} \\ 0 & 0 & 0 & 0 \\ c_{n+1} & c_{n+1} & c_{n+1} & c_{n+1} - 2^n \\ 0 & 0 & 0 & 0 \end{pmatrix}.
 \end{aligned}$$

(The matrices with odd indices are not interesting, because the number of words w of length $2n + 1$ such that A ends in an accepting state while processing the word w is zero)

We can see that $k = 3/4$ is good enough for definition of the equiloadingness. Indeed, for $n = 2l$ the maximally used state is q_0 with load $2c_l + 2^{l-1}$, the average load is $(8c_l - 2^l)/4$ and $|L \cap \Sigma^n| = 2^l$. \square

4.8 Open Questions

4.8.1 Characterization

We left open the characterization of equiloading automata. The algebraic representation of automata can be turned into computer program, which determines k_i , such that A is equiloading at words of the length i with equiloadingness constant k_i . After examining matrices Δ with small size, we observed that if a sum of each row or column in Δ is equal to 2, and $\delta_{(i+1) \bmod n, i} \geq 1$, then $\{k_i\}_{i=0}^\infty$ seems to be convergent.

Definition 4.3. Let ψ be a permutation of elements $0, 1, \dots, n-1$. We shall say that a directed graph G is *defined by the permutation ψ* , if

$$\forall i \in \{0, \dots, n-1\} \quad (i, \psi(i)) \in E(G).$$

Conjecture 4.1 (Two-cycles equiloading automata). Let ψ_1, \dots, ψ_k be permutations over $|Q|$ elements. Let A be an automaton such that the graphical representation of A is $G_0 \cup \bigcup_{i=0}^k G_i$, where $G_0 = (V, E_0)$ is a directed graph containing cycle through all states and $G_i = (V, E_i)$ is a directed graph defined by the permutation ψ_i . Then A is equiloading.

4.8.2 Equiloadingness Preserving Transformations

There are two automata transformations we conjecture to be equiloadingness preserving. First of them is a change of set of accepting states in such a way, that every state is

used on some $w \in L(A)$.

The second transformation is m -regular splitting of automaton A defined as follows.

Definition 4.4. Let $A = (Q, \Sigma, \delta_A, q_0, F)$ be an automaton, let m be a nonzero natural number. By an m -regular splitting of automaton A we obtain an automaton $B = (Q \times \{1, \dots, m\}, \Sigma, \delta_B, (q_0, 1), F_B)$, where $F_B \subseteq F \times \{1, \dots, m\}$ and for the transition function δ_B holds that

$$\forall p, q \in Q \ \exists i, j \in \mathbb{N} \setminus \{0\} \quad \delta_A(p, x) = q \Rightarrow \delta_B((p, i), x) = (q, j).$$

Moreover every state is accessible:

$$\forall p \in Q, \ \forall i \in \mathbb{N} \setminus \{0\} \quad \exists w \in L(B) \#[(p, i), w] > 0.$$

Conjecture 4.2. By an m -regular splitting of an equiloading automaton A we obtain an equiloading automaton.

4.8.3 Sufficient Condition for Language to Be in \mathcal{L}_{EQA}

In Theorem 4.3 we provide the necessary condition for automaton not to be equiloading. We believe that converse implication holds as we state in the following conjecture. When the minimal-state automaton A for a language fulfils the inequality (4.5) it suffices to split states of A in such a way, that A will be equiloading. However, it is not clear that such a splitting is possible. In Example 4.3 we show an automaton for which such a splitting of states exists.

Conjecture 4.3. Let L be a language. If for the minimal-state automaton A for the language L it holds that

$$\forall p, q \in Q \ \exists \ell \in \mathbb{R}^+ \ \exists n_0 \in \mathbb{N} \ \forall n \in \mathbb{N}, \ n > n_0 \quad \# [p, L \cap \Sigma^n] \leq \ell \# [q, L \cap \Sigma^n], \quad (4.5)$$

then $L \in \mathcal{L}_{\text{EQA}}$.

Example 4.3. Consider the language $L = \{aaa, bbb\}^*$. The minimal-state automaton A for this language is shown in Figure 4.6. This automaton is not equiloading, as we showed in Example 4.1. However, it fulfils the inequality (4.5) because

$$\frac{\# [q_0, L \cap \Sigma^{3k}]}{\# [q_1, L \cap \Sigma^{3k}]} = 2 + \frac{2}{k} \leq 3.$$

According to the above conjecture, there should be an equiloading automaton B that accepts the language L . Indeed, such an automaton exists as we can see in Figure 4.6. To show equiloadingness of the automaton B , we determine the load of the state q_0 , which is used the most. On all words of length $n = 3m$, the load of q_0 is equal to triples consisting of a (a-triples) plus one (the initial use). The number of a-triples is

between 0 and m . Furthermore, there are m choose i words of length n with i a-triples. Hence, the load of q_0 on words of length $3m$ is

$$\#[q_0, L \cap \Sigma^{3m}] = \sum_{i=0}^m \binom{m}{i} (i+1) = 2^{m-1}m + 2^m.$$

The automaton B is equiloading, because

$$2^{m-1}m + 2^m - \frac{(3m+1)2^m}{6} = \frac{5 \cdot 2^m}{6} = \frac{5}{6}|L \cap \Sigma^n|.$$

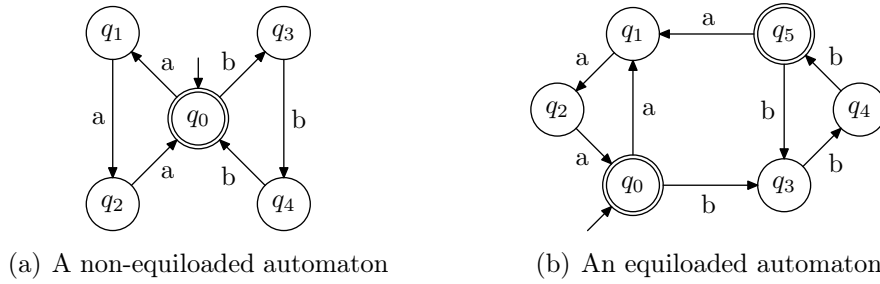


Figure 4.6: (a) A non-equiloading and (b) an equiloading automaton for the language $L = \{aaa, bbb\}^*$

Chapter 5

Automata Equiloading on Sequences of Words

In this chapter, we shall extend the previous definitions of equiloading automata from words to sequences of words. According to Definition 3.1 the automaton is equiloading, if it is equiloading on each word. Sometimes, it is better to think about the load of an automaton while it is computing at many inputs. (Batch processing.) Definition 4.1 can be understood as an intermediate step to this point of view. It tells us that there can be some sequence of inputs, sorted by lengths of words, on which an automaton will load each state equally. As we will see in this chapter, Definition 4.1 can be taken as a special case of the definition of an automaton equiloading on a sequence of words.

5.1 Definition

Firstly, we shall define a sequence of words. We shall only consider DFA that accept infinite languages. For our purposes, a sequence of words $S = w_1, w_2, \dots$ is an infinite sequence of words from a language $L(A)$ accepted by a given automaton A . Moreover, words in a sequence will not be repeated, thus $w_i = w_j \Rightarrow i = j$.

We shall denote by $S(i, j)$ the subsequence of S starting at the i -th word and ending at the j -th word.

Definition 5.1. Let $A = (Q, \Sigma, \delta, q_0, F)$ be a deterministic finite automaton. Let S be a sequence of words from $L(A)$. The automaton A is *equiloading on S* if there exists an ascending function $f : \mathbb{N} \rightarrow \mathbb{N}$ and a function $k : \mathbb{N} \rightarrow \mathbb{R}^+$ such that for all $i \in \mathbb{N}$ and all $p, q \in Q$ it holds that

$$|\#[p, S(f(i), f(i+1) - 1)] - \#[q, S(f(i), f(i+1) - 1)]| \leq k(i)(f(i+1) - f(i)).$$

The function k is said to be an *equiloading tolerance*. The function f is said to be a *windows-defining function*.

5.2 Equivalent Form

Notation. The function $\text{symb}(S(i, j)) = \sum_{w \in S(i, j)} |w|$ gives the number of symbols in the subsequence $S(i, j)$.

Remark. For the sake of brevity, we shall often use notation f_i instead of $f(i)$ and k_i instead of $k(i)$.

Lemma 5.1. A DFA $A = (Q, \Sigma, \delta, q_0, F)$ is equiloading on a sequence S if and only if there exists an ascending function $f : \mathbb{N} \rightarrow \mathbb{N}$ and a function $k' : \mathbb{N} \rightarrow \mathbb{R}^+$ such that for all $i \in \mathbb{N}$ it holds that

$$\max_{q \in Q} (\# [q, S(f_i, f_{i+1} - 1)]) - \text{avg}(S(f_i, f_{i+1} - 1)) \leq k'_i(f_{i+1} - f_i), \quad (5.1)$$

where

$$\text{avg}(S(i, j)) = \frac{\text{symb}(S(i, j)) + j + 1 - i}{|Q|}$$

is the average load of states while A processes words from the subsequence $S(i, j)$. Furthermore, there exists a $c \in \mathbb{R}^+$ such that $c \cdot k'(i) \geq k(i)$ for k from Definition 5.1.

Proof. If A is equiloading on a sequence S , then similarly to previous definitions we consider the most- and the least-used state. It is easy to see that the average load of states on the subsequence $S(f_i, f_{i+1} - 1)$ is greater than or equal to the load of the least used state, hence the inequality (5.1) holds for $k_i = k'_i$.

Conversely, suppose that the inequality (5.1) holds. Then, for a given i , the load of each state is less than

$$\text{avg}(S(f_i, f_{i+1} - 1)) + k'_i(f_{i+1} - f_i).$$

Also, the load of each state is greater than

$$\text{avg}(S(f_i, f_{i+1} - 1)) - k'_i(f_{i+1} - f_i)(|Q| - 1).$$

Therefore, the difference between loads of arbitrary states p and q is not greater than

$$k'_i(f_{i+1} - f_i) + k'_i(|Q| - 1)(f_{i+1} - f_i) = k'_i \cdot |Q| \cdot (f_{i+1} - f_i).$$

Hence, automaton A is equiloading on the sequence S with equiloading tolerance $k_i = k'_i |Q|$. \square

Theorem 5.1. For a given automaton A , a sequence S , and an ascending function $f : \mathbb{N} \rightarrow \mathbb{N}$, there is a function $k : \mathbb{N} \rightarrow \mathbb{R}^+$ such that A is equiloading on the sequence S with a windows-defining function f and an equiloading tolerance k .

Proof. Define $k(n)$ by $k(i) = \max_{w \in S(f(i), f(i+1)-1)} |w| + 1$. We shall show, that A is equiloading on the sequence S with the equiloading tolerance k . Let us bound from

above the maximal load of a state at the subsequence $S(f(i), f(i+1) - 1) = S_i$:

$$\#[q, S_i] \leq \text{symb}(S_i) \leq (f(i+1) - f(i)) \cdot (\max_{w \in S_i} |w| + 1) = (f(i+1) - f(i)) \cdot k(i).$$

Hence, A is equiloading on the sequence S . \square

Thus for a large equiloadingness tolerance the notion of equiloadingness becomes trivial. We shall therefore consider “reasonably small” f and k in what follows. It comes from the following theorem, that “reasonably small” in the case of the equiloadingness tolerance means constant, or at least sub-linear.*

Theorem 5.2. For every given automaton A there exists a sequence S of all words in $L(A)$ and a windows-defining function f such that A is equiloading on S with the equiloadingness tolerance $k(n) = \Omega(n)$.

Proof. The sequence we are looking for is the lexicographically ordered sequence S .[†] Let $f(i) = i$. This means, that we will consider windows of constant length 1. It is easy to see that

$$\#[q, S(i, i)] = \#[q, w_i] \leq |w_i| + 1 \leq |Q|i + 1.$$

The last inequality follows from the fact that if there is a word of length n in an infinite language accepted by the automaton A , then in A has to be a cycle of length at most $|Q|$, therefore there exists a word of length at most $n + |Q|$. From the above inequality we obtain that it suffices to take the equiloadingness tolerance $k(i) = |Q|i + 1 = \Omega(n)$. \square

It should be possible to define the meaning of “reasonably small” value even for the case of the windows-defining function f . We conjecture that if an automaton is equiloading on a sequence with a windows-defining function f_1 and a constant equiloadingness tolerance, then it is equiloading on another sequence with a linear windows-defining function f and a constant equiloadingness tolerance.

5.3 Impact of Order of Words on Equiloadingness Tolerance

We shall discuss the impact of choosing a sequence for an automaton A , on which we want A to be equiloading. As the first example, we shall consider an automaton $A = (\{q_0, q_1\}, \{a, b\}, \delta, q_0, \{q_0, q_1\})$, where the transition function δ is defined by

$$\delta(q_0, a) = q_0, \quad \delta(q_0, b) = q_1, \quad \delta(q_1, b) = q_1.$$

Let S be the lexicographically ordered sequence of words in the language $L(A)$, i.e., $S = \varepsilon, a, b, aa, ab, bb, \dots$

*Thus, in the following we shall consider only constant equiloadingness tolerance.

[†]It suffices to consider any sequence $S' = w_1, w_2, \dots, w_n$ for which $|w_i| \leq |w_{i+1}|$.

Theorem 5.3. For the automaton A and the sequence S defined above, if $k(n)$ is a constant, and A is equiloading on S , then for any non-zero $l \in \mathbb{N}$ it holds $f(n) > ln$ for sufficiently large n , where f is a windows-defining function from Definition 5.1. (The size of windows is greater than constant.)

Proof. For a given constant $k' = k(n)$ and l , we shall find a number n such that A is not equiloading on $S(ln, ln + l - 1)$ with the equiloading tolerance k' . Let $n = 2lk' + 1$. Then the subsequence $S(ln, ln + l - 1) = S(2(lk')^2 + lk', 2(lk')^2 + lk' + l - 1)$ consists of words $a^{2lk'}, a^{2lk'-1}b, \dots, a^{2lk'-l+1}b^{l-1}$. The load of the state q_0 on this subsequence is

$$\#[q_0, S(ln, ln + l - 1)] = 2lk' + 1 + 2lk' + 2lk' - 1 + \dots + 2lk' - l + 1 = (1/2)l(4lk' - l + 3).$$

The load of q_1 is just $(1/2)l(l-1)$, therefore A is not equiloading with the equiloading tolerance k' . \square

Theorem 5.4. Consider A defined above. There is a sequence S' of words in $L(A)$ such that A is equiloading on S' with the equiloading tolerance $k(n) = 0$ and a linear windows-defining function f , $f(n) = 2n$.

Proof. If $f(n) = 2n$, the size of each window is equal to 2. We want to choose pairs of words from $L(A)$, such that the load of q_0 on the pair is equal to the load of q_1 . First, we realize that by $\#[q_0, w]$ and $\#[q_1, w]$ w is exactly determined: $w = a^{\#[q_0, w]-1}b^{\#[q_1, w]}$. We shall construct S' in pairs as follows. For the i -th pair, we choose the first non-used word w'_{2i} from S and find a pair w'_{2i+1} , which is also a non-used word from S , such that $\#[q_0, w'_{2i}] + \#[q_0, w'_{2i+1}] = \#[q_1, w'_{2i}] + \#[q_1, w'_{2i+1}]$. The sequence S' looks like $\varepsilon, bb, a, abb, b, abbb, \dots$. Then, A is equiloading on the sequence S' with $k(n) = 0$ and $f(n) = 2n$. \square

Now, we shall consider another automaton $B = (Q, \{a, b\}, \delta_B, q_0, q_0)$, a minimal automaton for a language $L = \{aaa, bbb\}^*$. This automaton, shown in Figure 4.6(a) in the previous chapter, is defined by transition function

$$\begin{aligned} \delta_B(q_0, a) &= q_1, & \delta_B(q_1, a) &= q_2, & \delta_B(q_2, a) &= q_0, \\ \delta_B(q_0, b) &= q_3, & \delta_B(q_3, b) &= q_4, & \delta_B(q_4, b) &= q_0. \end{aligned}$$

It is easy to see that for all $w \in L$ it holds that

$$\#[q_0, w] = \#[q_1, w] + \#[q_2, w] + 1$$

We shall prove that there is no sequence S such that B is equiloading on S with constant equiloading tolerance (and arbitrary f).

Theorem 5.5. There is an automaton B such that for any sequence S and an ascending function f it holds that B is not equiloading on S with the windows-defining function f and a constant equiloading tolerance.

Proof. Consider the automaton B defined above and the subsequence of S from $f(i)$ to $f(i+1) - 1$. Without loss of generality, we may assume that q_1 is the least used state on that subsequence. Then it holds that

$$\begin{aligned}
& \#[q_0, S(f_i, f_{i+1} - 1)] - \#[q_1, S(f_i, f_{i+1} - 1)] \geq \\
& \geq \frac{\text{symb}(S(f_i, f_{i+1} - 1))}{3} + (f_{i+1} - f_i) - \frac{\text{symb}(S(f_i, f_{i+1} - 1))}{6} \\
& \geq \frac{\text{symb}(S(f_i, f_{i+1} - 1))}{6} + (f_{i+1} - f_i) \\
& = (f_{i+1} - f_i) \left(\frac{\text{symb}(S(f_i, f_{i+1} - 1))}{6(f_{i+1} - f_i)} \right).
\end{aligned}$$

Hence, the equiloading tolerance of B on sequence S should be at least

$$k(i) \geq \left(\frac{\text{symb}(S(f_i, f_{i+1} - 1))}{6(f_{i+1} - f_i)} \right) \notin \mathcal{O}(1).$$

It is easy to see that there is i_0 such that if $i > i_0$ the number of symbols in the subsequence is greater than the number of words in this subsequence. \square

Chapter 6

Conclusion

In this thesis we discussed three approaches to the equiloadedness property for DFA. We have established a characterization of strictly equiloaded automata and, based on this characterization, we proved closure properties of the class $\mathcal{L}_{\text{SEQA}}$.

We analyzed the characterization of equiloaded automata. After proving some basic results about equiloaded automata, we proved a necessary condition for a language to be in the family \mathcal{L}_{EQA} . We introduced an algebraic representation which makes it easier to determine the equiloadedness of an automaton. We proved closure properties of the family \mathcal{L}_{EQA} . Although we did not find a characterization based on a graphical representation of an automaton, we were able to formulate a conjecture on this characterization.

Next, we investigated equiloadedness property for sequences of words. We have shown that every automaton is equiloaded on every sequence given a sufficiently large equiloadedness tolerance. Furthermore, we proved that for each automaton there exists a sequence such that the automaton is equiloaded on the sequence with a linear equiloaded tolerance and a linear windows-defining function f . We have shown an existence of an automaton which is not equiloaded on any sequence with a constant equiloadedness tolerance.

Although we provide solutions to many interesting problems concerning equiloadedness, there are still some open problems, mainly in the area of equiloadedness on sequences of words. Among the most prominent are:

Equiloaded automata: a characterization of equiloaded automata and/or the family \mathcal{L}_{EQA} , transformations preserving equiloadedness, a sufficient condition for a language to be in \mathcal{L}_{EQA} .

Automata equiloaded on sequences: f - k trade-off, operations over sequences.*

These questions may be an interesting topic for further research. Our results suggests that it may be worthwhile to study a balanced use of resources on a different model (NFA, push-down automata, ...) or with different resources (transitions between states).

*For this problem, we need to consider sequences of words from $L \subseteq L(A)$.

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Abstrakt

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Predkladaná práca sa zaoberá štúdiom rovnomerného využívania prostriedkov vo výpočtoch. Uvažujeme konkrétny výpočtový model, deterministický konečný automat, a stavy takéhoto automatu ako prostriedok, ktorý sa má používať rovnomerne. V tomto modeli definujeme potrebné pojmy pre rovnomerné využívanie stavov a dokazujeme výsledky. V práci prezentujeme tri možné prístupy k rovnomernosti – *striktnú rovnomernosť*, *rovnomernosť* a *rovnomernosť na postupnostiach slov*. Analyzujeme triedy automatov a jazykov vzhľadom na tieto prístupy.

V práci prinášame charakterizáciu triedy jazykov, pre ktoré existuje striktne rovnomerný automat. Dokazujeme uzáverové vlastnosti tejto triedy.

Analyzujeme triedu jazykov, pre ktoré existuje rovnomerný automat, dokazujeme uzáverové vlastnosti tejto triedy, ako aj nutnú podmienku, ktorú musí jazyk spĺňať, aby do tejto triedy patrilo. Definujeme množinu transformácií automatov, ktoré zachovávajú rovnomernosť.

V súvislosti s rovnomernosťou na postupnostiach slov skúmame vplyv rôznych usporiadaní slov na mieru nerovnomernosti pre rovnomernosť na postupnostiach slov. Skúmame rovnomernosť na postupnostiach slov pre rôzne ohraničenia miery nerovnomernosti.

Naše výsledky môžu poslúžiť ako príklad pre podobný výskum pre iné výpočtové modely a prostriedky.

KLÚČOVÉ SLOVÁ: rovnomerne využívané automaty, rovnomerné využívanie prostriedkov, deterministické konečné automaty